

Nonlinearly Constrained Problems

$$\min_{\vec{x} \in \mathbb{R}^n} F(\vec{x}) \text{ subject to } c(\vec{x}) = 0 \in \mathbb{R}^m$$

- No complete characterization of the *feasible set*
- *e.g.*

$$c_1(x_1, x_2) = (x_1 - 1)^2 + x_2^2 - 1$$

$$c_2(x_1, x_2) = x_2 - \alpha$$

Implicit Function Theorem

- Suppose $f(x^o, y^o) = 0$
- Can we *solve* for $y(x)$?

Implicit Function Theorem

We are given a mapping

$f : D \subset \mathbb{R}^n \times \mathbb{R}^m \mapsto \mathbb{R}^m$ that is

\mathcal{C}^1 on the region D , and a point

$(x^o, y^o) \in D$ such that

$f(x^o, y^o) = 0 \in \mathbb{R}^m$. Suppose that

the $(m \times m)$ Jacobian matrix

$$\begin{bmatrix} \frac{\partial f_1}{\partial y_1} & \frac{\partial f_1}{\partial y_2} & \cdots & \frac{\partial f_1}{\partial y_m} \\ \frac{\partial f_2}{\partial y_1} & \frac{\partial f_2}{\partial y_2} & \cdots & \frac{\partial f_2}{\partial y_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial y_1} & \frac{\partial f_m}{\partial y_2} & \cdots & \frac{\partial f_m}{\partial y_m} \end{bmatrix} \bigg|_{(x_0, y_0)}$$

is non-singular. Then there are neighborhoods

S_x of x^o and S_y of y^o , such that for any $\hat{x} \in S_x$ the equation $f(\hat{x}, y) = 0$ has a *unique* solution $y = h(\hat{x}) \in S_y$. Moreover, the mapping $h : S_x \mapsto R^m$ is differentiable with

$$\frac{\partial h}{\partial x} = - \left(\frac{\partial f}{\partial y} \right)^{-1} \circ \left(\frac{\partial f}{\partial x} \right).$$

Constrained Minimization

2-D Case

- Consider $n = 2$, $m = 1$.

$$\min_{(x,y)} F(x, y) \text{ subject to } c(x, y) = 0.$$

- Suppose (x^*, y^*) is a solution

Constrained Minimization

2-D Case

$$f(x, y, \epsilon) \equiv \begin{bmatrix} F(x, y) - F(x^*, y^*) + \epsilon \\ c(x, y) \end{bmatrix}$$

- Note that $f(x^*, y^*, 0) = 0 \in \mathbb{R}^2$
- Suppose (x^*, y^*) is a solution of

the problem and suppose

$$\begin{bmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} \\ \frac{\partial c}{\partial x} & \frac{\partial c}{\partial y} \end{bmatrix} (x^*, y^*)$$

has *rank* two.

- By the *IFT* we can *solve* for x, y in terms of ϵ .
- Choose $\epsilon > 0$ and we have a

point that satisfies the
constraints and yields

$$F(x, y) = F(x^*, y^*) - \epsilon < F(x^*, y^*)$$

➤ This means (x^*, y^*) is not a
solution of the problem.

➤ The matrix

$$\begin{bmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} \\ \frac{\partial c}{\partial x} & \frac{\partial c}{\partial y} \end{bmatrix}_{(x^*, y^*)}$$

must have rank less than two.

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$$\min_{\vec{x} \in \mathbb{R}^n} F(\vec{x}) \text{ subject to } c(\vec{x}) = 0 \in \mathbb{R}^m$$

If \vec{x}^* is a solution, then the matrix

$$\begin{bmatrix} \nabla F \\ \nabla c_1 \\ \vdots \\ \nabla c_m \end{bmatrix}_{\vec{x}^*}$$

must have rank less than $m + 1$.

Nonlinearly Constrained Problems

Lagrange Multiplier Theorem

$$\min_{\vec{x} \in \mathbb{R}^n} F(\vec{x}) \text{ subject to } c(\vec{x}) = 0 \in \mathbb{R}^m$$

If \vec{x}^* is a solution, then there are scalars $\lambda_0, \lambda_1, \dots, \lambda_m$, not all zero,

such that

$$\lambda_0 \nabla F + \lambda_1 \nabla c_1 + \dots + \lambda_m \nabla c_m = 0$$

Nonlinearly Constrained Problems

Lagrange Multiplier Theorem

- Define the *Lagrangian* function

by

$$\mathcal{L}(\vec{x}, \lambda_0, \lambda_1, \dots, \lambda_m) = \lambda_0 F(\vec{x}) + \sum_{i=1}^m \lambda_i c_i(\vec{x})$$

- If \vec{x}^* is a solution then there is a $\lambda_0, \vec{\lambda}$ so that $\nabla \mathcal{L} = 0$
- When can we assume $\lambda_0 \neq 0$?

► Suppose that the matrix

$$\begin{bmatrix} \nabla c_1 \\ \vdots \\ \nabla c_m \end{bmatrix}_{\vec{x}^*}$$

has full rank ($= m$), then

$$\lambda_0 \neq 0.$$